

# Industrial Shared Wireless Communication System – Use Case of Autonomous Guided Vehicles

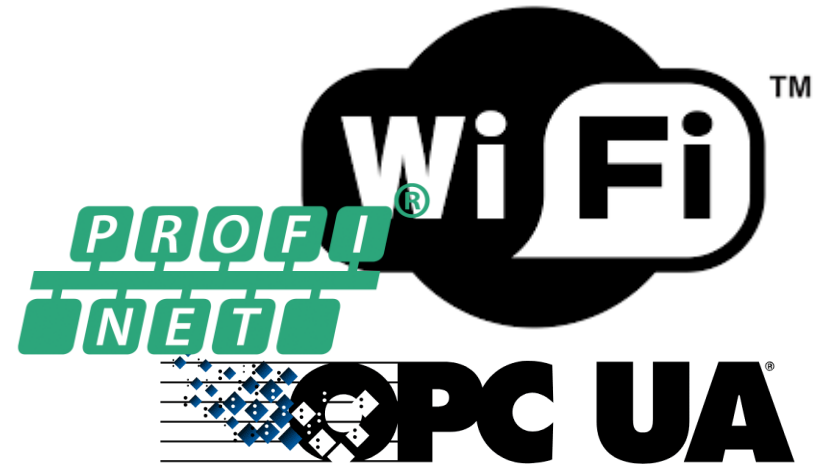
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# Agenda

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1. Infrastructure
2. Profinet IO
3. OPC UA
4. Experimental research
5. Connection quality
6. Future works



# Goal

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Checking the influence of additional network traffic to the parameters of the RealTime industrial network.

Profinet + OPC UA

# Goals

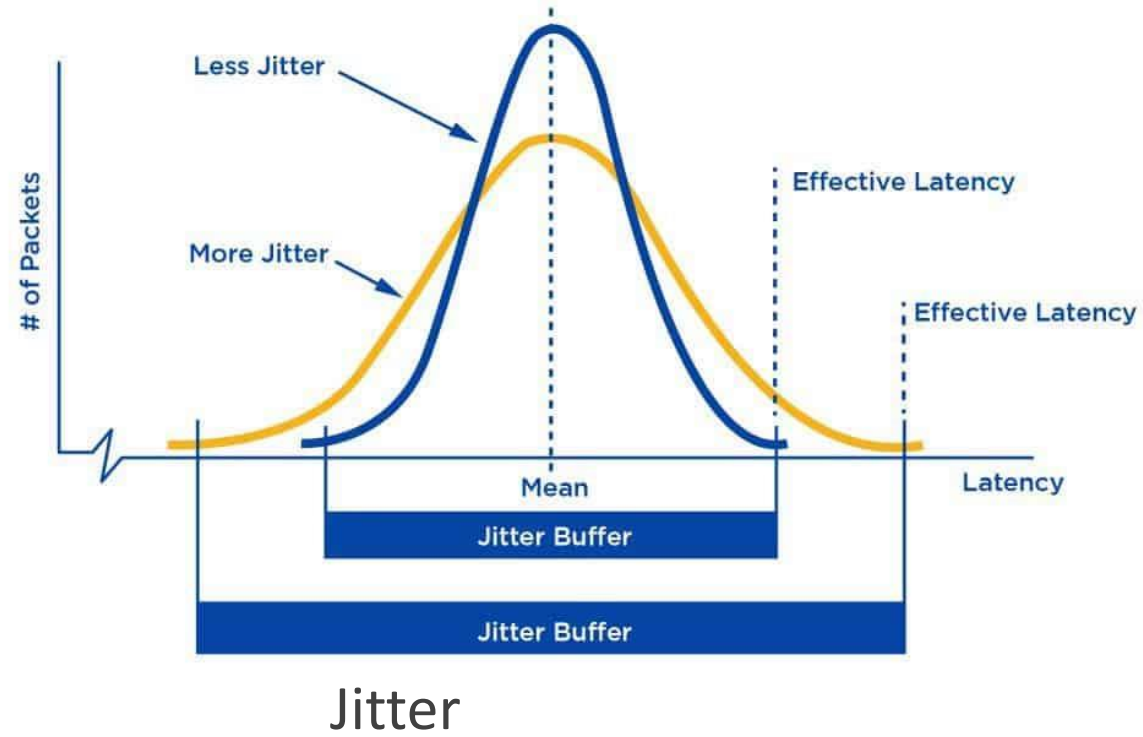
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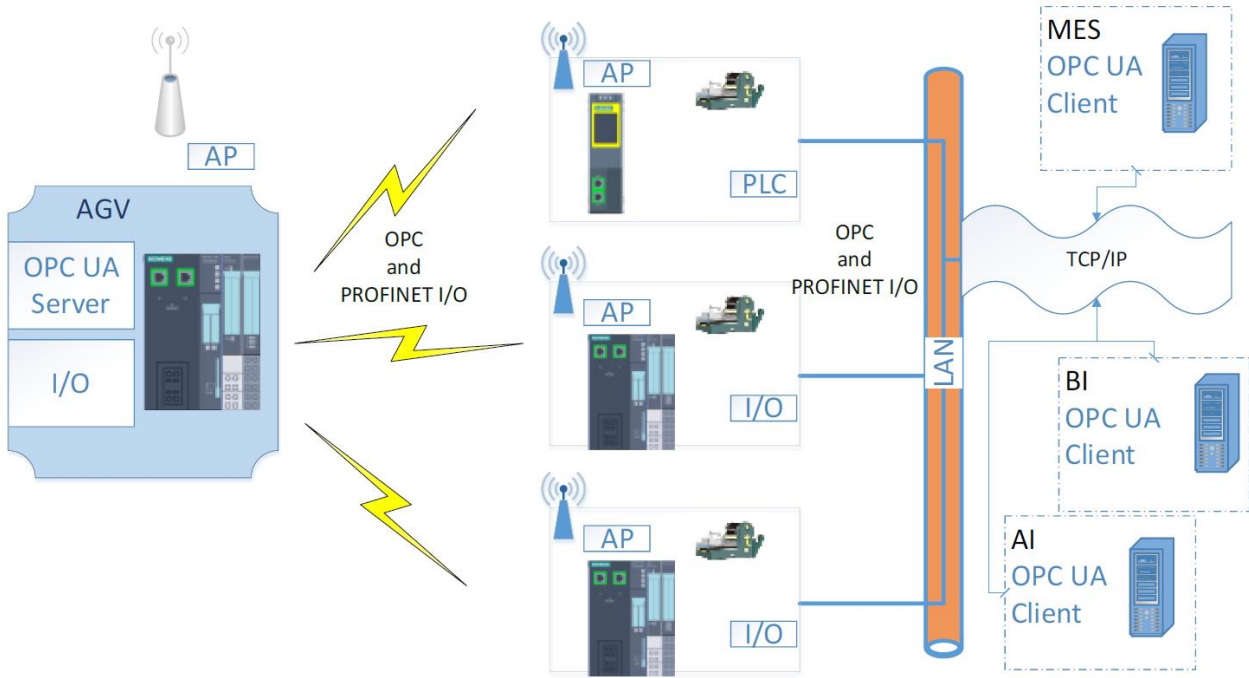
Latency

# Goals

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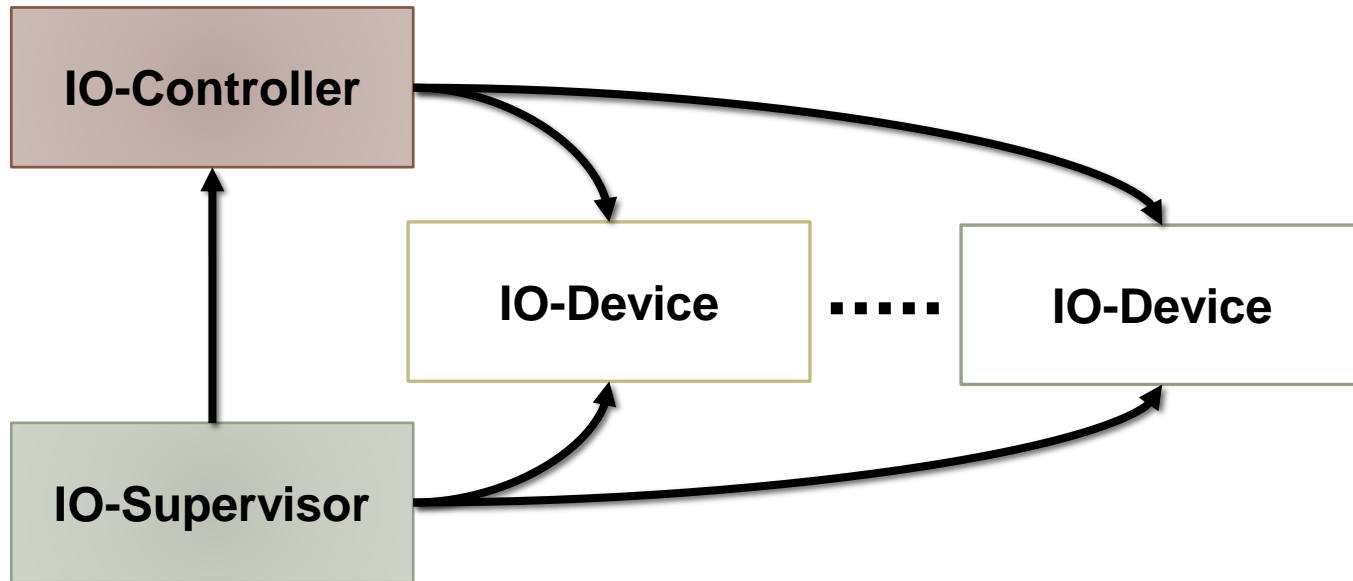


# Infrastructure



# Profinet

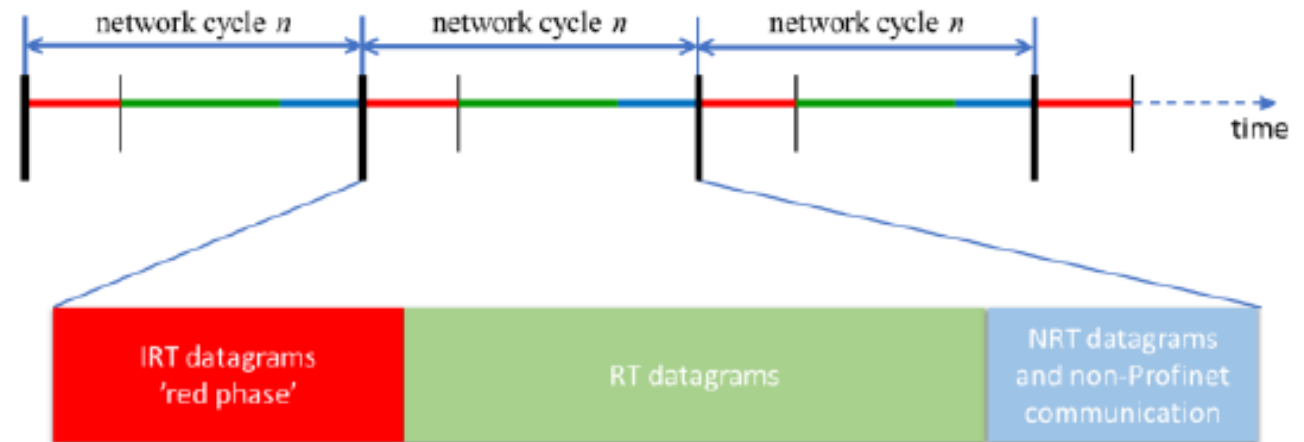
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# Profinet

- ***NRT No Real Time*** – TCP/UDP channel, configuration, parameters
- ***RT Real Time*** – Real Time channel,
- ***IRT Isochronous Real Time*** – IRT channel, isochronous communication with Real Time

Devices work in Full Duplex mode



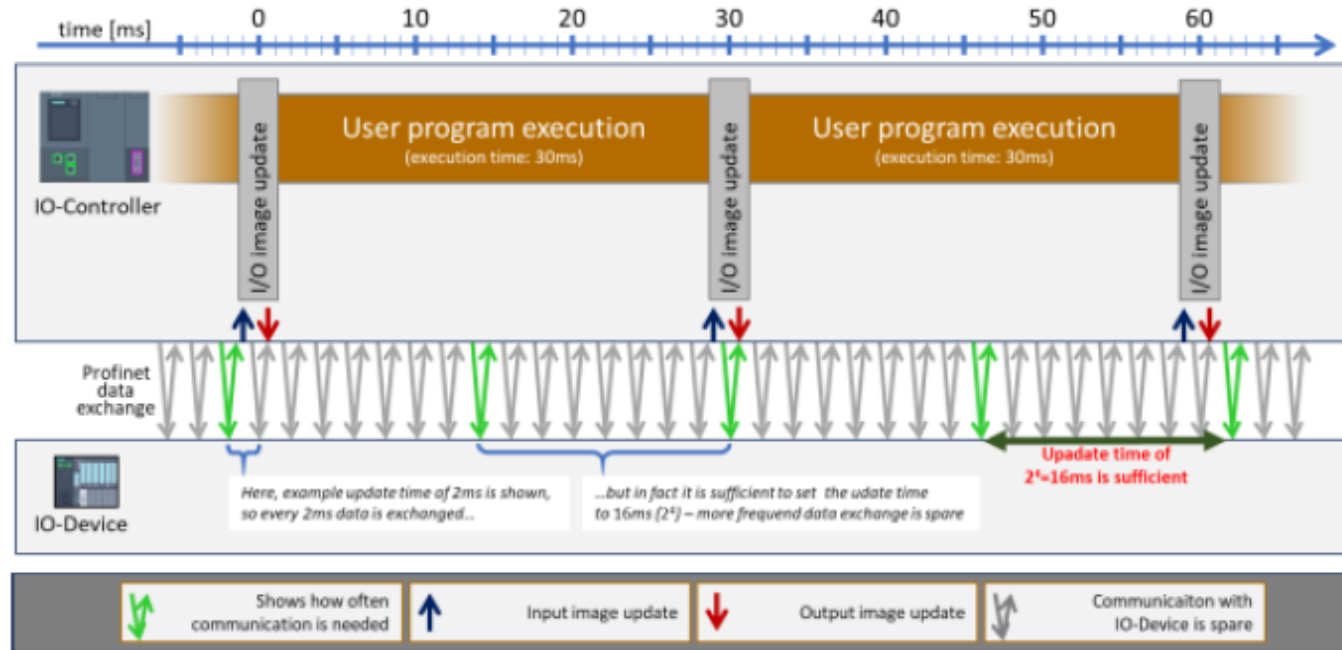


# Profinet IRT

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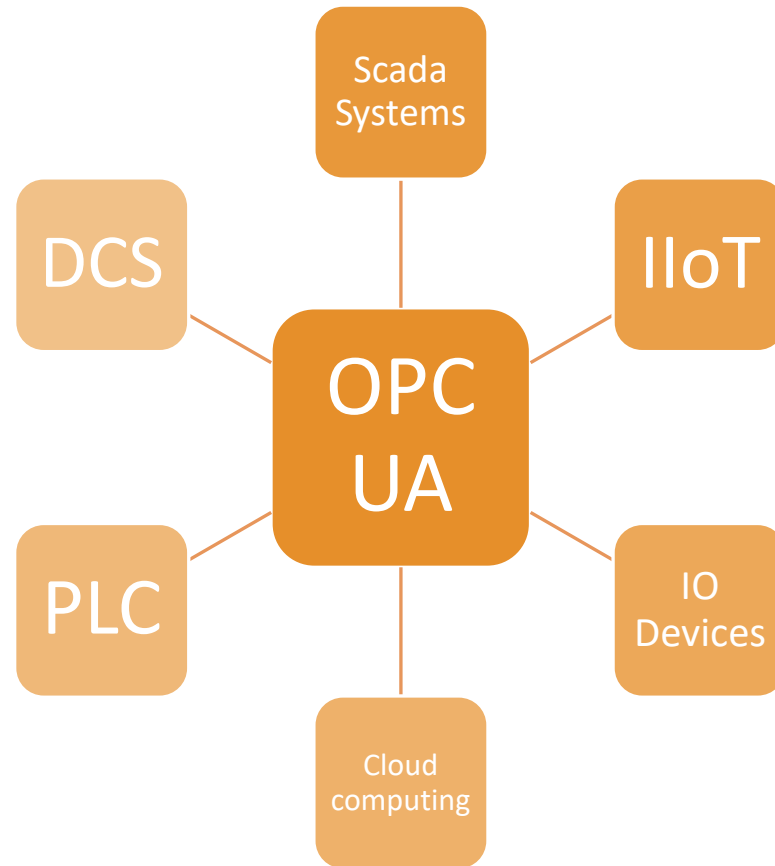
# Profinet IRT



Why the update time of a Profinet IO-Device should be adjusted to the PLC cycle time ?

# OPC UA

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# OPC UA – publisher/subscriber

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~~Client~~ ← → ~~Server~~

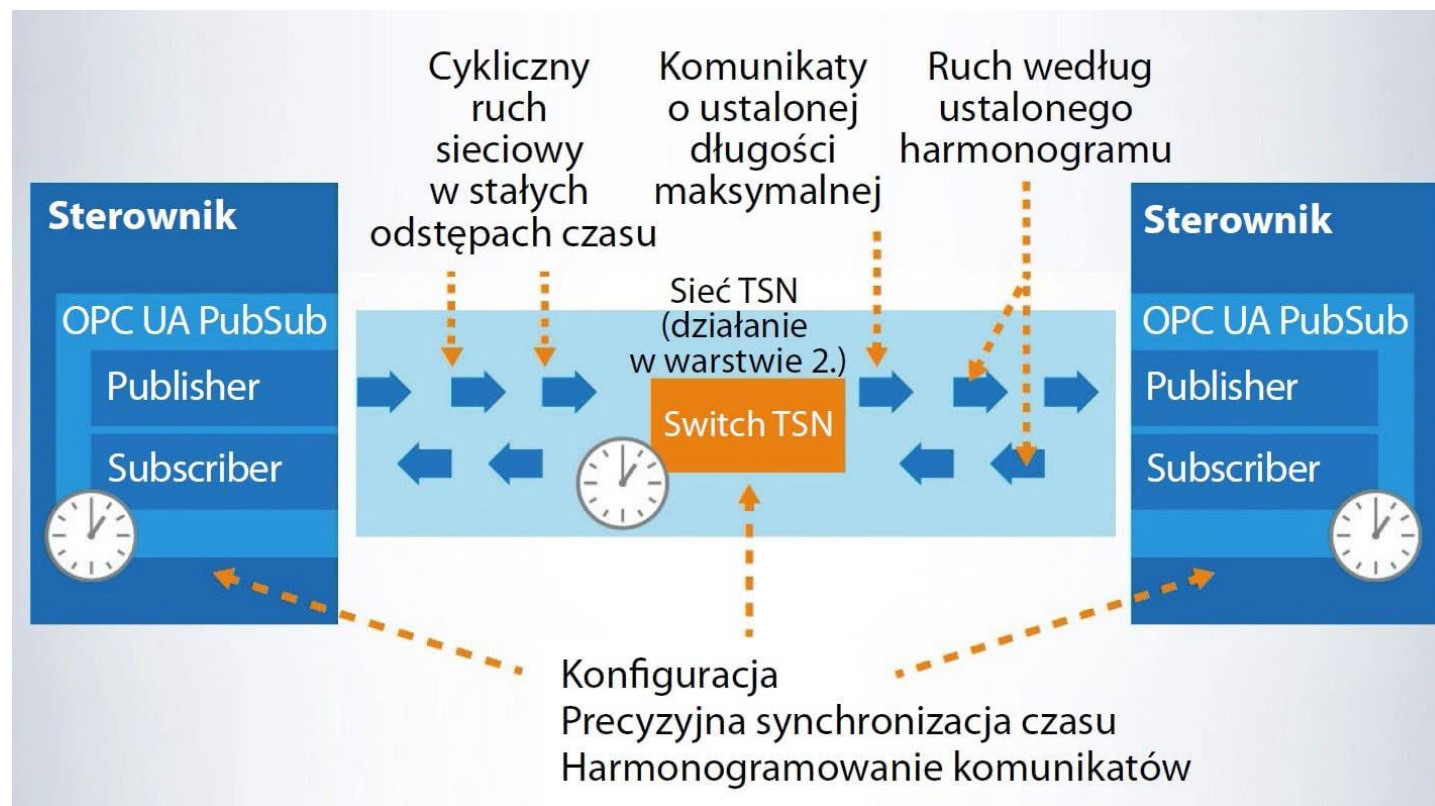
Publisher ← → Subscriber

# OPC UA – publisher/subscriber

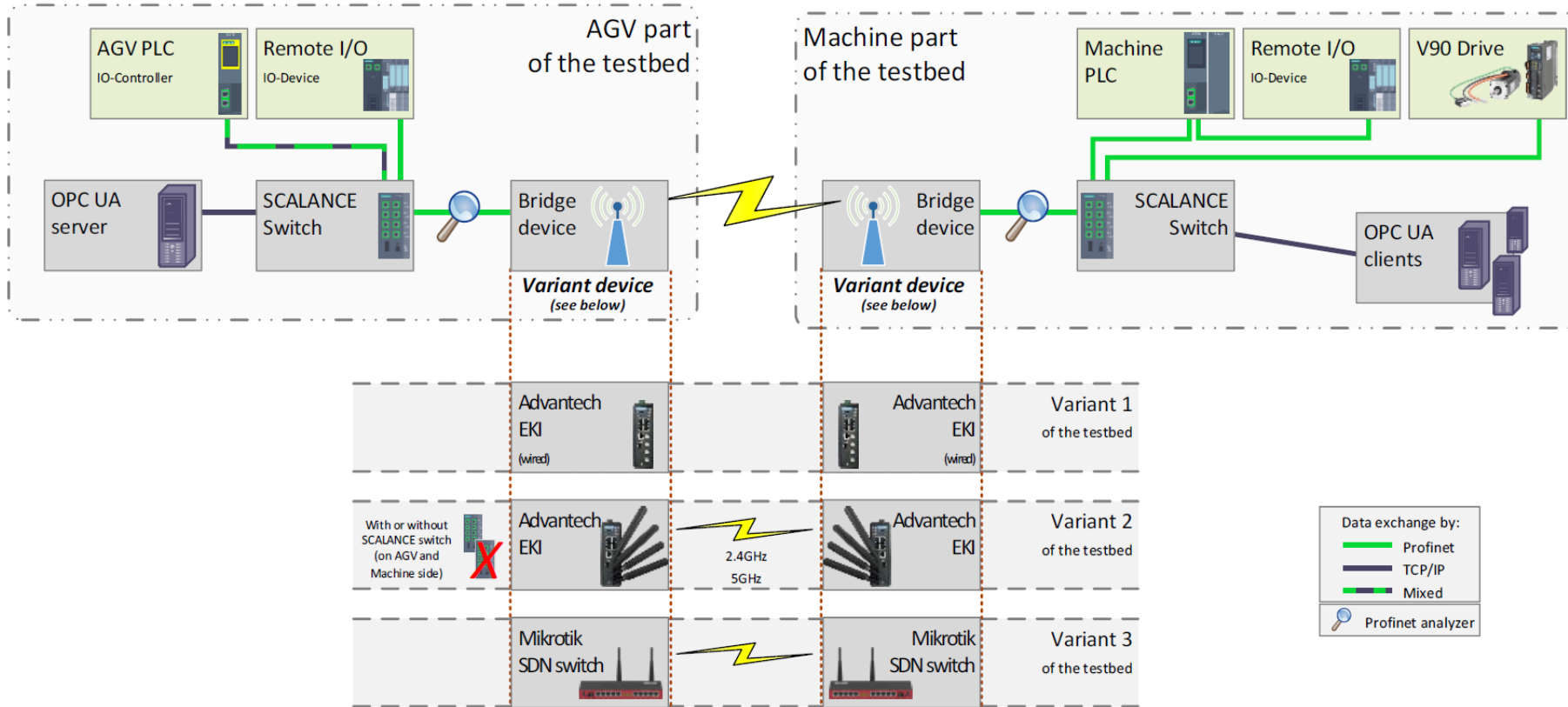
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- ▶ No requirement for continuous connection to the server
- ▶ Reduction of the required hardware resources
- ▶ Easy access to data when data is collecting from several systems

# OPC UA Time Sensitive Network



# Experimental research



# Experimental research

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Testbed configuration		Update time			
		2ms	4ms	64ms	128ms
Wired connection	Jitter	10.7%	4.78%	0.1%	~0.1%
	Jitter [ms]	0.2	0.19	0.06	~0.06
Wireless 2.4GHz	Jitter	--	--	--	14.1%
	Jitter [ms]	--	--	--	18.0
Wireless 5GHz	Jitter	--	--	18.8%	7.6%
	Jitter [ms]	--	--	12.0	9.72



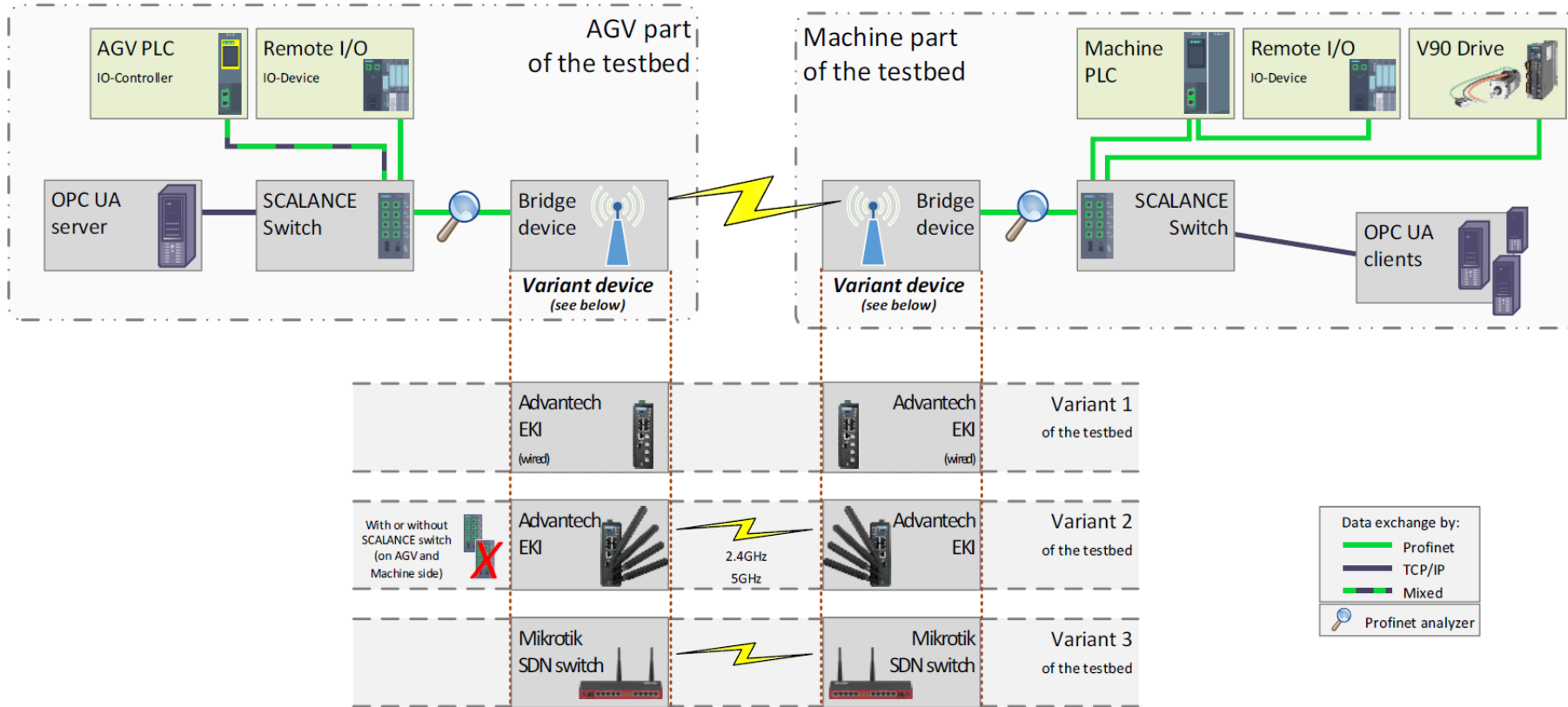
# Experimental research

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Measurement setup	Wired		2.4Ghz		5Ghz	
	Jitter %	Jitter [ms]	Jitter %	Jitter [ms]	Jitter %	Jitter [ms]
No OPC UA server	2.4%	3.0	14.1%	18.0	18.8%	12.0
OPC UA server active – only background communication with AGV	3.2%	4.1	20.4%	26.1	17.6%	11.3
1 client on 1 PC computer	3.7%	4.7	39.2%	50.2	19.4%	12.4
2 clients on 2 PC computers	4.4%	5.6	32.5%	41.6	17.1%	10.9
4 clients on 4 PC computers	5.5%	7.0	35.7%	45.7	17.3%	11.1
6 clients on 6 PC computers	6.8%	8.7	37.0%	47.4	19.8%	12.7
8 clients on 6 PC computers	7.3%	9.3	38.9%	49.8	19.9%	12.7
10 clients on 6 PC computers	8.5%	10.9	40.2%	51.5	19.9%	12.7
12 clients on 6 PC computers	10.8%	13,8	41.8%	53.5	20.6%	13.2

Results for wireless connection with an update time of 128ms

# Experimental research



# Experimental research

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Measurement setup	Wired		2.4Ghz	
	Jitter %	Jitter [ms]	Jitter %	Jitter [ms]
No OPC UA server	2.4%	3.0	14.1%	18.0
OPC UA server active – only background communication with AGV	3.2%	4.1	20.4%	26.1
1 client on 1 PC computer	3.7%	4.7	39.2%	50.2
2 clients on 2 PC computers	4.4%	5.6	32.5%	41.6
4 clients on 4 PC computers	5.5%	7.0	35.7%	45.7
6 clients on 6 PC computers	6.8%	8.7	37.0%	47.4
8 clients on 6 PC computers	7.3%	9.3	38.9%	49.8
10 clients on 6 PC computers	8.5%	10.9	40.2%	51.5
12 clients on 6 PC computers	10.8%	13.8	41.8%	53.5

Measurement setup	Jitter %	Jitter [ms]
No OPC UA server	12,6%	16.1
UPC UA server active, no clients	24.5%	31.4
1 client on 1 PC computer	23.4%	29.9
2 clients on 2 PC computers	37.6%	48.1
3 clients on 2 PC computers	65.9%	84.4
4 clients on 2 PC computers	110.5%	141.4

Results for wireless connection with an update time of 128ms without Scalance switch

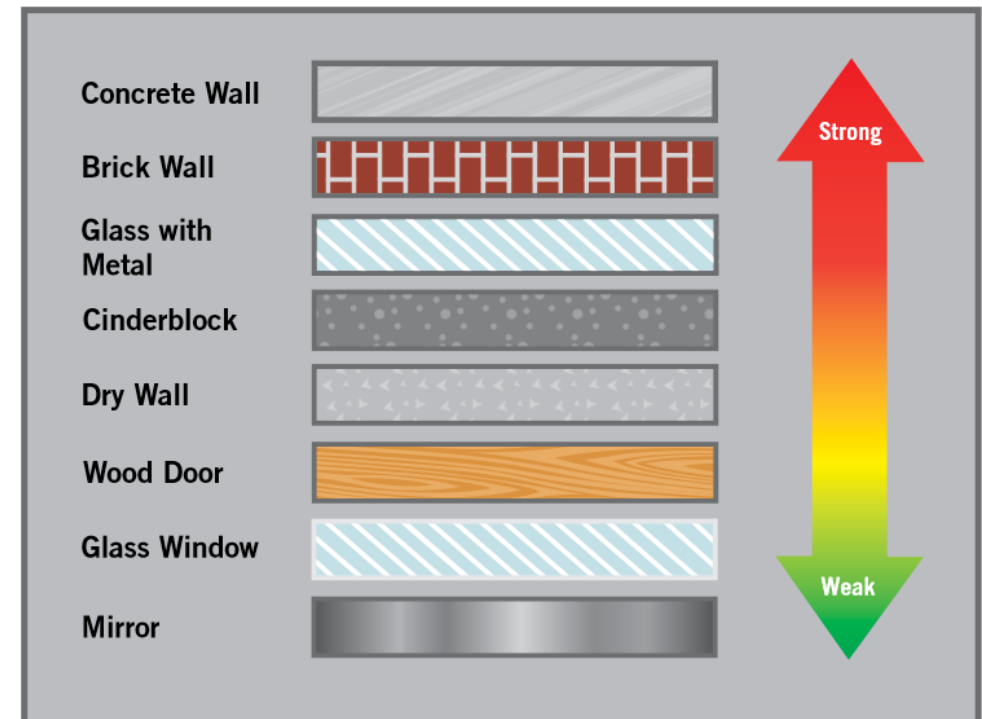
# Connection quality

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IEEE Standard	Maximum Linkrate
WiFi 6	600 to 9608 Mbit/s
WiFi 5	433 to 6933 Mbit/s
WiFi 4	72 to 600 Mbit/s
802.11g	3 to 54 Mbit/s
802.11b	1.5 to 54 Mbit/s
802.11a	1 to 11 Mbit/s

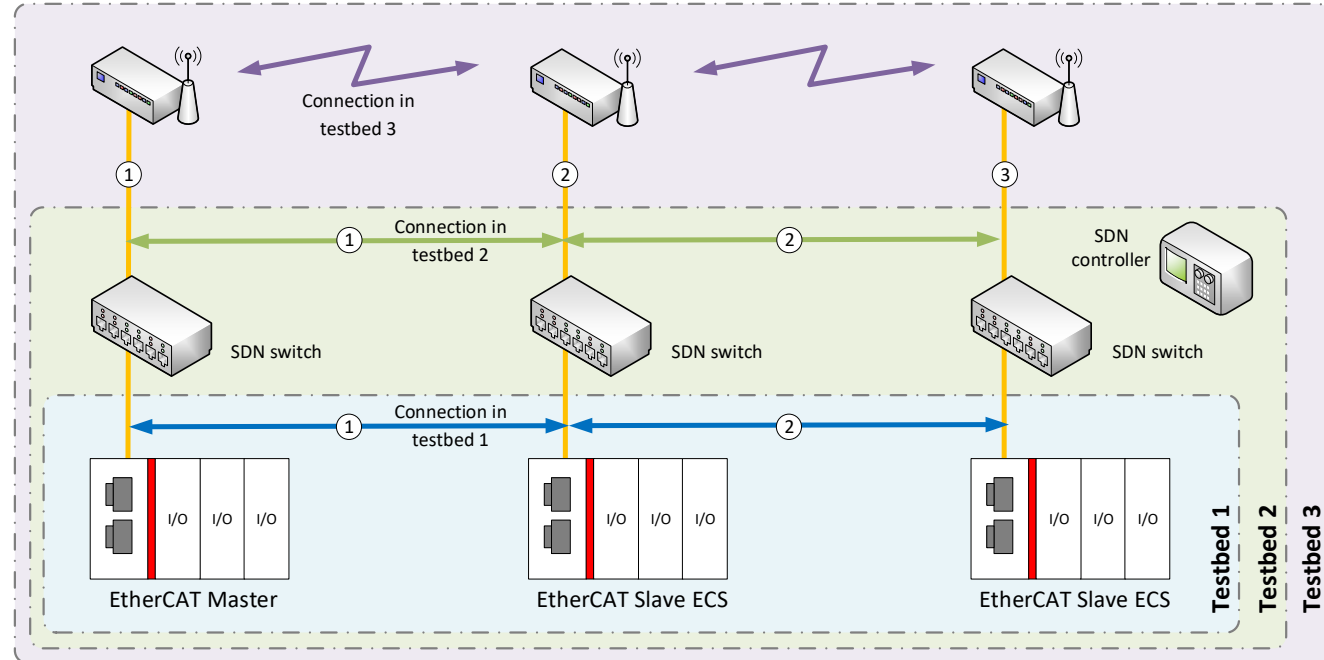
# Connection quality

Material	Thickness [cm]	Attenuation [dB]
Brick	30	9
	10	7
Concrete	30	11
Wood	4	2,5
Glass	2	4,5



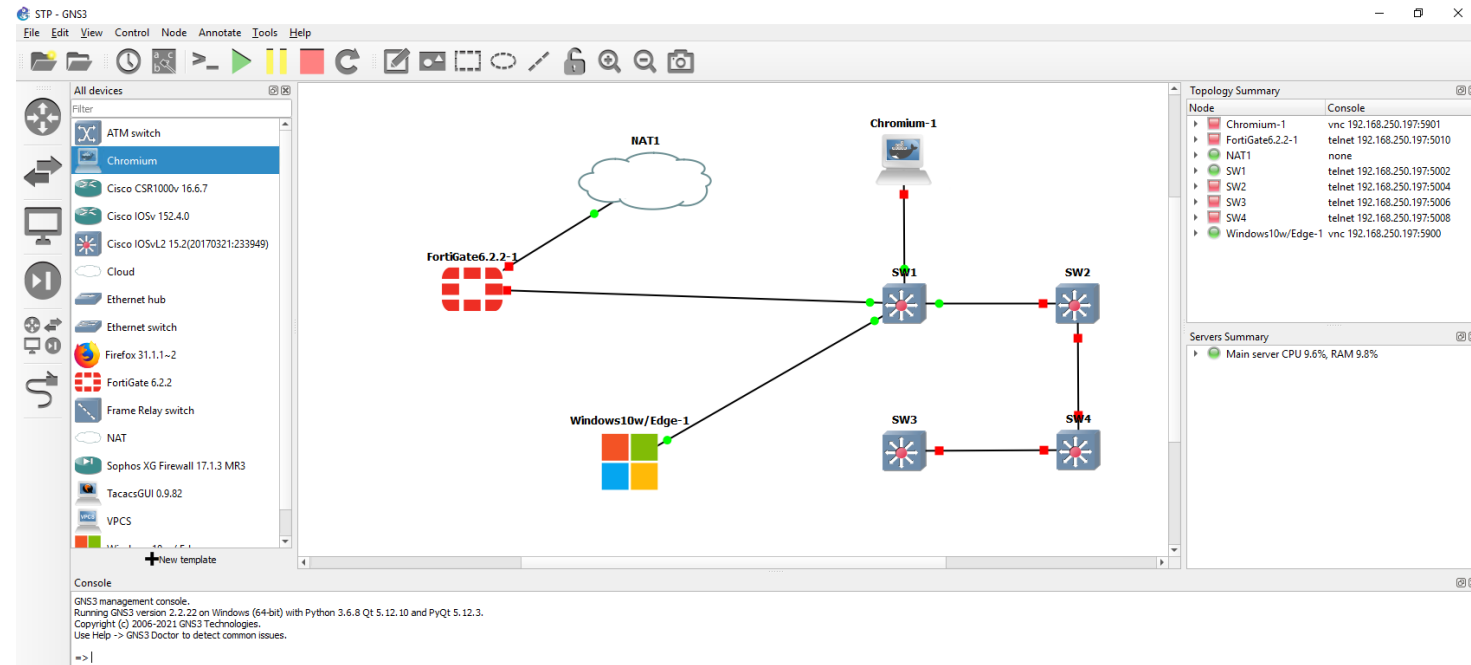
# Future works

- Change network protocol – EtherCAT



# Future works

## ► Simulation in GNS3 environment



Thank you for your attention

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